

Proving the nonexistence of algebraic solutions of differential equations

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RWTH-Aachen–2011

Part I

The problem

Stating the problem

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Solve the system of differential equations

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$$\begin{aligned}\dot{x} &= a(x, y) \\ \dot{y} &= b(x, y),\end{aligned}$$

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$$\begin{aligned}\dot{x} &= a(x, y) \\ \dot{y} &= b(x, y),\end{aligned}$$

where a and b are polynomials in x and y . More concisely,

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Solve the system of differential equations

$$\begin{aligned}\dot{x} &= a(x, y) \\ \dot{y} &= b(x, y),\end{aligned}$$

where a and b are polynomials in x and y . More concisely,

$$\dot{X} = F(X),$$

where $X = (x, y)$ and $F = (a, b)$ is a polynomial vector field.

What does it mean to solve an equation?

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The canonical definition

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Find a parameterized curve $C(t)$ such that

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The canonical definition

Find a *parameterized* curve $C(t)$ such that

$$\dot{C} = F(C(t)).$$

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What if the function were also known implicitly?

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Suppose we know a function $H = H(x, y)$ whose set of zeros is C .

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Question

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Suppose we know a function $H = H(x, y)$ whose set of zeros is C .

Question

How can we say that the curve is a solution of the system using H instead of the parameterization?

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$$H(C(t)) = 0.$$

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Thus,

$$\frac{d}{dt}H(C(t)) = 0.$$

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Thus,

$$\frac{dx}{dt} \frac{\partial H}{\partial x}(C(t)) + \frac{dy}{dt} \frac{\partial H}{\partial y}(C(t)) = 0.$$

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What does it mean to solve an equation?

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$$H(C(t)) = 0.$$

Thus,

$$\left(a \frac{\partial H}{\partial x} + b \frac{\partial H}{\partial y} \right) (C(t)) = 0;$$

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Thus,

$$\left(a \frac{\partial H}{\partial x} + b \frac{\partial H}{\partial y} \right) (C(t)) = 0;$$

which is equivalent to

$$(F \cdot \nabla H)(C(t)) = 0.$$

What does it mean to solve an equation?

First integral

What does it mean to solve an equation?

First integral

A function $H(x, y)$ is a first integral of the system $\dot{X} = F(X)$ if

$$F(x, y) \cdot \nabla H = 0,$$

as a function of x and y .

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Key property

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First integral

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Key property

If H is a first integral of $\dot{X} = F(X)$ then every integral curve of this system is contained in a level curve of H .

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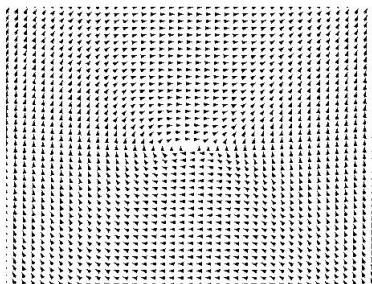
The system $\dot{X} = F(X)$, defined by the vector field

What does it mean to solve an equation?

The system $\dot{X} = F(X)$, defined by the vector field $F(x, y) = (2y, 3x^2)$

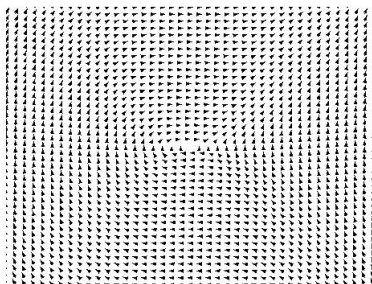
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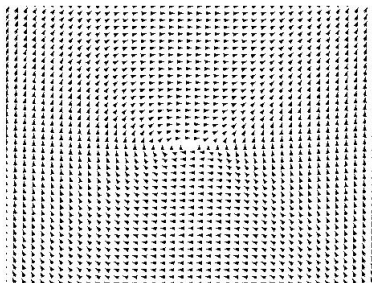
What does it mean to solve an equation?

The system $\dot{X} = F(X)$, defined by the vector field $F(x, y) = (2y, 3x^2)$ has first integral $H(x, y) = y^2 - x^3$.



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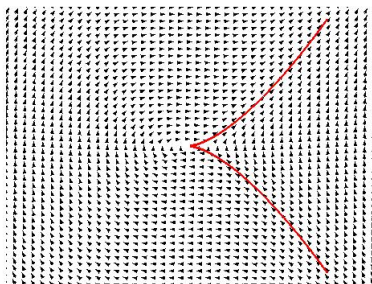
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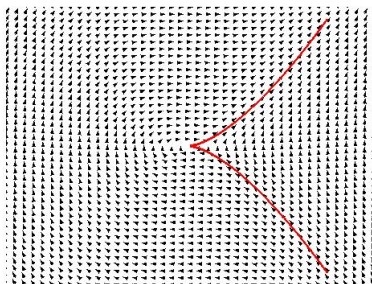
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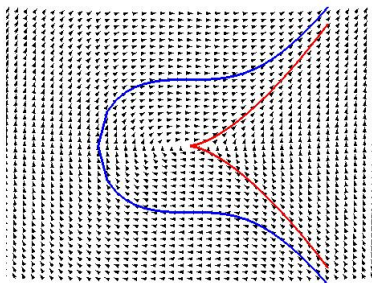
$$H(x, y) = 0 \text{ and}$$



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$$H(x, y) = 0 \quad \text{and} \quad H(x, y) = 1.$$



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Given a polynomial vector field $F(X)$,

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Given a polynomial vector field $F(X)$, compute a first integral of the differential equation $\dot{X} = F(X)$.

Stating the problem

The problem

Given a *polynomial* vector field $F(X)$, compute a first integral of the differential equation $\dot{X} = F(X)$.

Polynomial differential equations

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- Bianchi models in cosmology;
- etc.

Part II

The 19th century

C. G. J. Jacobi, 1842





1.

. De integratione aequationis differentialis

$$(A + A'x + A''y)(x dy - y dx) \\ - (B + B'x + B''y) dy + (C + C'x + C''y) dx = 0.$$

(Auct. C. G. J. Jacobi, prof. ord. Regiom.)



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(Auct. C. G. J. Jacobi, prof. ord. Regiom.)

Solves a differential equation with linear coefficients, with a long calculation.

Alfred Clebsch, 1872

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Ueber eine Fundamentalaufgabe der Invarianten-
theorie.

Von
A. Clebsch.

Der Königl. Gesellschaft der Wissenschaften überreicht am 2. März 1872.



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Geometric interpretation of differential equations using homogeneous coordinates.

G. Darboux, 1878

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MÉLANGES.

MÉMOIRE SUR LES ÉQUATIONS DIFFÉRENTIELLES ALGÈBRIQUES
DU PREMIER ORDRE ET DU PREMIER DEGRÉ;

PAR M. G. DARBOUX.



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MÉMOIRE SUR LES ÉQUATIONS DIFFÉRENTIELLES ALGÈBRIQUES
DU PREMIER ORDRE ET DU PREMIER DEGRÉ;
PAR M. G. DARBOUX.

Introduces the method that defined the research line we will pursue in this talk.

Darboux's key idea

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$$(F(x, y) \cdot \nabla H)(C(t)) = 0.$$

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so that,

$$(F(x, y) \cdot \nabla H)(p) = 0 \text{ whenever } H(p) = 0.$$

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If H and F are polynomial, then so is

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Therefore, the conclusion above implies that,

$$F(x, y) \cdot \nabla H = GH,$$

for some polynomial $G = G(x, y)$, called the co-factor of H .

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Therefore, the conclusion above implies that,

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for some polynomial $G = G(x, y)$, called the co-factor of H .

Assuming that H is reduced, this follows from Hilbert's Nullstellensatz.

Darboux's key idea

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Invariant curve

Darboux's key idea

Invariant curve

An algebraic curve $H(x, y) = 0$ is invariant under the system $\dot{X} = F(x, y)$ if

$$F(x, y) \cdot \nabla H = GH,$$

Darboux's key Theorem

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Existence of first integral

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If $\dot{X} = F(X)$ has enough invariant curves, then it admits a first integral.

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Degree of a vector field

If $F = (a, b)$, for polynomials a and b , then

$$\deg(F) = \max\{\deg(a), \deg(b)\}$$

Darboux's key Theorem

Existence of first integral

If $\dot{X} = F(X)$ has *more than $\deg(F)(\deg(F) - 1)/2$ invariant curves*, then it admits a first integral.

Degree of a vector field

If $F = (a, b)$, for polynomials a and b , then

$$\deg(F) = \max\{\deg(a), \deg(b)\}$$

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If H is invariant under $\dot{X} = F(X)$ then

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$$\deg \left(a \frac{\partial H}{\partial x} + b \frac{\partial H}{\partial y} \right) = \deg(GH).$$

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Hence,

$$\max \left\{ \deg \left(a \frac{\partial H}{\partial x} \right), \left(b \frac{\partial H}{\partial y} \right) \right\} \geq \deg(GH).$$

Where does this bound come from?

If H is invariant under $\dot{X} = F(X)$ then

$$F(x, y) \cdot \nabla H = GH,$$

Hence,

$$\max \left\{ \deg(a) + \deg \left(\frac{\partial H}{\partial x} \right), \deg(b) + \deg \left(\frac{\partial H}{\partial y} \right) \right\} \geq \deg(GH).$$

Where does this bound come from?

If H is invariant under $\dot{X} = F(X)$ then

$$F(x, y) \cdot \nabla H = GH,$$

Hence,

$$\max\{\deg(a) + \deg(H) - 1, \deg(b) + \deg(H) - 1\} \geq \deg(GH).$$

Where does this bound come from?

If H is invariant under $\dot{X} = F(X)$ then

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If H is invariant under $\dot{X} = F(X)$ then

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In particular, G is an element of the subspace of polynomials of degree $\leq \deg(F) - 1$,

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If H is invariant under $\dot{X} = F(X)$ then

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Hence,

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In particular, G is an element of the subspace of polynomials of degree $\leq \deg(F) - 1$, which has dimension

$$\frac{(\deg(F) - 1) \deg(F)}{2}.$$

Proof of Darboux's key Theorem

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$$d = \frac{(\deg(F) - 1) \deg(F)}{2}$$

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p_1, \dots, p_k be curves invariant under $\dot{X} = F(X)$;

Proof of Darboux's key Theorem

$$d = \frac{(\deg(F) - 1) \deg(F)}{2}$$

$\nabla p_j \cdot F = g_j p_j$, where $1 \leq j \leq k$ and $\deg(g_j) \leq \deg(F) - 1$.

Proof of Darboux's key Theorem

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$\nabla p_j \cdot F = g_j p_j$, where $1 \leq j \leq k$ and $\deg(g_j) \leq \deg(F) - 1$.

If $k > d$ then g_1, \dots, g_k are linearly dependent,

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If $k > d$ then g_1, \dots, g_k are linearly dependent, so

$$c_1 g_1 + \dots + c_k g_k = 0 \text{ for scalars } c_1, \dots, c_k.$$

Proof of Darboux's key Theorem

Hypotheses:

- $F \cdot \nabla p_j = g_j p_j$, where $1 \leq j \leq k$;
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Define

$$h = p_1^{c_1} \cdots p_k^{c_k}$$

then

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$$F \cdot \nabla h = F \cdot \nabla (p_1^{c_1} \cdots c_k p_k^{c_k})$$

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Define

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$$F \cdot \nabla h = F \cdot (c_1 p_1^{c_1-1} \cdots p_k^{c_k} \nabla p_1 + \cdots + p_1^{c_1} \cdots c_k p_k^{c_k-1} \nabla p_k)$$

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$$F \cdot \nabla h = c_1 p_1^{c_1} \cdots p_k^{c_k} g_1 + \cdots + p_1^{c_1} \cdots c_k p_k^{c_k} g_k$$

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- $c_1 g_1 + \cdots + c_k g_k = 0$ for scalars c_1, \dots, c_k .

Define

$$h = p_1^{c_1} \cdots p_k^{c_k}$$

then

$$F \cdot \nabla h = p_1^{c_1} \cdots p_k^{c_k} (c_1 g_1 + \cdots + c_k g_k)$$

Proof of Darboux's key Theorem

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Hence h is a first integral of F .

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Since $2 \cdot 1 + (-1) \cdot 2 = 0$,

$$h = (y + 2)^2(2x + 2y + 3)^{-1},$$

is a first integral of $\dot{X} = F(X)$.

Also in Darboux's paper

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- solutions for some equations with quadratic coefficients;
- a study of the singular points of the differential equations.

The singularities of an equation

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The singular points of $\dot{X} = F(X)$ are the points of the plane at which F vanishes.

From now on we will assume that $F = (a, b)$ with $\gcd(a, b) = 1$. Geometrically, this means that F has finitely many singularities.

Counting singularities after Darboux

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Given a polynomial h of degree d in two variables let h_d be its homogeneous component of degree d .

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Note for the experts

The condition $ya_n = xb_n$ means that the one-dimensional direction field that F defines in the projective plane has no singularities at infinity.

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C'est là un problème qui, semble-t-il, aurait dû tenter les géomètres, et cependant ils s'en sont fort peu occupés. Depuis l'œuvre magistrale de M. Darboux, publiée dans le *Bulletin des Sciences mathématiques*, la question a été négligée pendant vingt ans et il a fallu, pour attirer de nouveau sur elle l'attention qu'elle méritait, que l'Académie des Sciences la proposât comme sujet du concours pour le Grand Prix des Sciences mathématiques. Deux Mémoires furent récompensés, M. Painlevé obtint le prix et M. Autonne une mention honorable: l'un de ces deux Mémoires a été publié dans les *Annales de l'École Normale supérieure* et l'autre dans le *Journal de l'École Polytechnique*.

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Also in various textbooks up to the early 20th century.

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“it is evidently sufficient to find an upper limit to the degree of the algebraic invariant curves”.

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One more problem

One more problem

Poincaré's problem

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Given a vector field F with polynomial coefficients, find a bound on the degree of the algebraic curves invariant under F as a function of some numerical invariant of F .

Part III

The 20th century

Reworks Darboux's results in the language of modern algebraic algebraic geometry:

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- detailed study of Jacobi equation in higher dimensions;
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- an algebraic curve invariant under a vector field must contain a singularity at least if we include the ones at infinity;
- a general equation of degree higher than 2 does not have any invariant curve.

Singularities on invariant curves

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Singularities on invariant curves

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Let $F = (a, b)$ be a polynomial vector field of degree n for which $ya_n = xb_n$. Any algebraic curve invariant under F must contain a singularity of F .

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Let h be the reduced polynomial in x and y that defines the curve.

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$$F \cdot \nabla h = gh$$

for some polynomial g of degree at most $n - 1$.

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Let h be the reduced polynomial in x and y that defines the curve.
If h is invariant under F

$$F(p) \cdot \nabla h(p) = g(p)h(p)$$

for some polynomial g of degree at most $n - 1$ and all singularities p of F .

Singularities on invariant curves

Let h be the reduced polynomial in x and y that defines the curve.
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$$\underbrace{F(p)}_{=0} \cdot \nabla h(p) = g(p)h(p)$$

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Singularities on invariant curves

Let h be the reduced polynomial in x and y that defines the curve.
If h is invariant under F and $h = 0$ contains no singularity of F

$$0 = g(p)h(p)$$

for some polynomial g of degree at most $n - 1$ and all singularities p of F .

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$$0 = g(p) \underbrace{h(p)}_{\neq 0}$$

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Thus,

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a contradiction.

The Poincaré problem in the 20th century

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Walcher, 2000 the field has nice singularities at infinity and
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Prelle and Singer, 1983 algorithm compute elementary solutions to
 $\dot{X} = F(X)$;

Singer, 1992 characterization of Liouvillian solutions of
 $\dot{X} = F(X)$;

Schlomiuk, 1993 characterization of quadratic fields that have a centre.

Part IV

The existence problem

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Since no efficient necessary and sufficient criterion for the existence of such curves is known, we will settle for a probabilistic test.

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Key point

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Key point

The x -coordinates of the singularities of F are all of them roots of p .

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We will proceed by contradiction, assuming that the field F has an invariant algebraic curve with rational coefficients.

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Because p generates $(a, b) \cap \mathbb{Q}[x]$.

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G acts transitively on the set of singularities of F :

$g \cdot (x_0, q(x_0)) = (g(x_0), q(g(x_0)))$ for any $g \in G$.

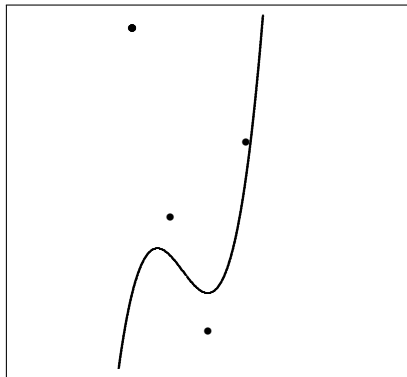
The proof: core argument

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The curve $h = 0$ and the singularities of F .

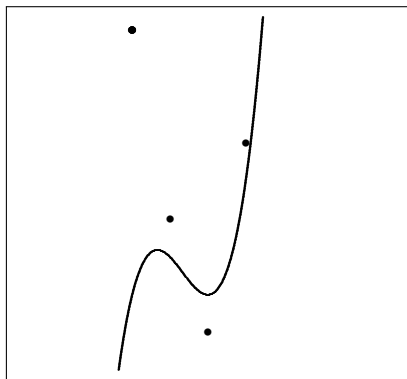
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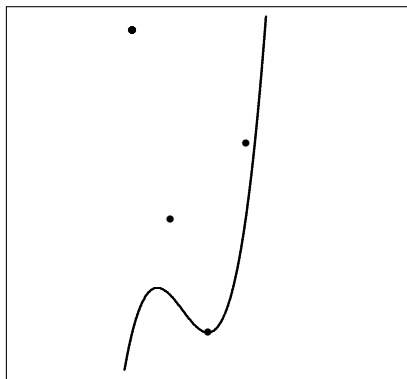
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Jouanolou's theorem: $h = 0$ must contain a singularity of F .

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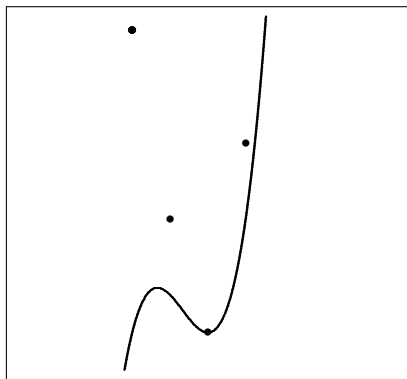
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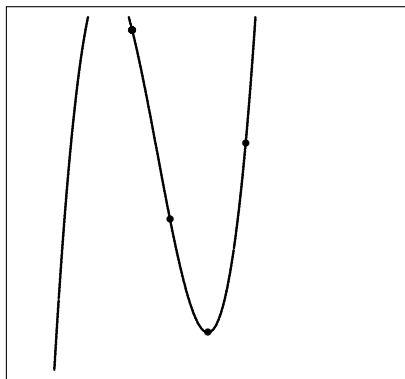
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G acts transitively on the singularities and h has rational coordinates.

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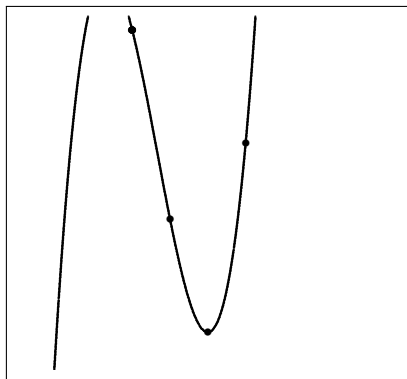
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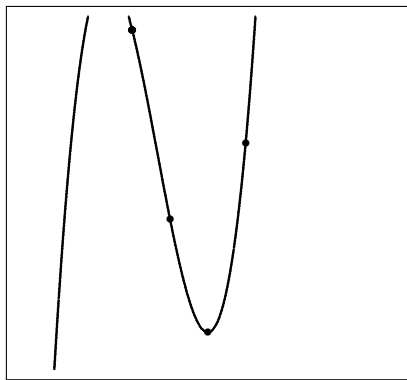
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Thus, $h(p) = 0$ whenever $F(p) = 0$,

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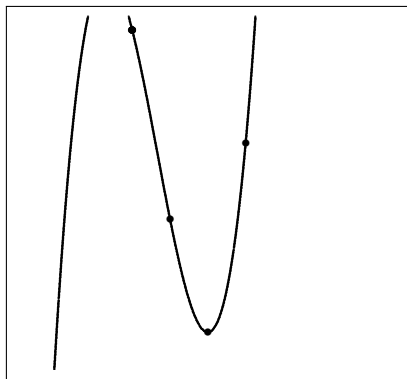
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Thus, $h(p) = 0$ whenever $F(p) = 0$, but is this possible?

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The proof: punch line

Since G acts transitively on the singularities of F we have that either

- $h = 0$ is smooth;
- $h = 0$ is singular at all the singularities of F .

In both cases the curve cannot contain all the singularities of F , hence the contradiction.

Further developments

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With M. da Silva Ferreira.

Part V

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