

Exam 2(February 26, 2003)

MAS4105 Linear Algebra I (F. Lübeck)

(1) Mark as true or false. (One point for each correct answer.)

Let $A = \begin{pmatrix} 1 & -1 & 3 & 0 \\ 1 & -2 & 4 & 1 \\ 0 & -1 & 1 & 1 \end{pmatrix} \in M_{3 \times 4}(\mathbb{R})$, $B = \begin{pmatrix} 1 & -1 & 3 & 0 \\ 0 & 1 & -1 & -1 \\ 0 & 0 & 0 & 0 \end{pmatrix} \in M_{3 \times 4}(\mathbb{R})$

and $C = \begin{pmatrix} 1 & -1 & 3 & 0 \\ 3 & 1 & -1 & -1 \\ 0 & 2 & -3 & 1 \\ 2 & 0 & -3 & 4 \end{pmatrix} \in M_{4 \times 4}(\mathbb{R})$.

- (a) The matrix product $D = AB$ is defined and $D_{2,3} = 5$. true: false:
- (b) The matrix product $F = BC$ is defined and $F_{1,3} = -5$. true: false:
- (c) The matrix B is in reduced row echelon form. true: false:
- (d) The matrix B can be obtained from A by two elementary row operations. true: false:
- (e) Each elementary row operation on B can be described by multiplication with an invertible matrix $E \in M_{3 \times 3}$ from the left. true: false:
- (f) Elementary row operations preserve the column space of a matrix. true: false:
- (g) The rank of A is 2. true: false:
- (h) The rank of a matrix is the maximal number of linearly independent columns it has. true: false:
- (i) If the rank of an $n \times n$ -matrix is n then its reduced echelon form is the identity matrix I_n . true: false:
- (j) The nullspace of A is a subspace of $\mathbb{R}^{4 \times 1}$ and has dimension 1. true: false:

(2) (three points) Let $C = \begin{pmatrix} 1 & 2 & 2 \\ -1 & -1 & 2 \\ 0 & 0 & 1 \end{pmatrix} \in M_{3 \times 3}(\mathbb{R})$ and $I_3 \in M_{3 \times 3}(\mathbb{R})$ the identity matrix. Compute the matrix $AAAA - I_3$.

(3) (four points) Compute the reduced row echelon form of the matrix

$$A = \begin{pmatrix} 1 & 2 & 3 & 1 & 2 & 3 \\ 2 & 4 & 6 & 1 & 2 & 5 \\ 3 & 6 & 9 & 4 & 8 & 3 \end{pmatrix} \in M_{3 \times 6}(\mathbb{R}).$$

Determine a basis of the nullspace $N(A)$.

(4) (three points) Compute the inverse of the matrix $\begin{pmatrix} 0 & -1 & 0 \\ -3 & 1 & -2 \\ -8 & 0 & -5 \end{pmatrix} \in M_{3 \times 3}(\mathbb{R})$.