

Why are we learning/developing this mathematics?

Two major scientific developments of the past 50 years:

- Complexity of nonlinear dynamical systems
- Development of information technologies

Structural stability is not generic

Homoclinic tangencies

- Newhouse Phenomenon - strange attractors and arbitrarily long stable periodic orbits intertwined in parameter space.

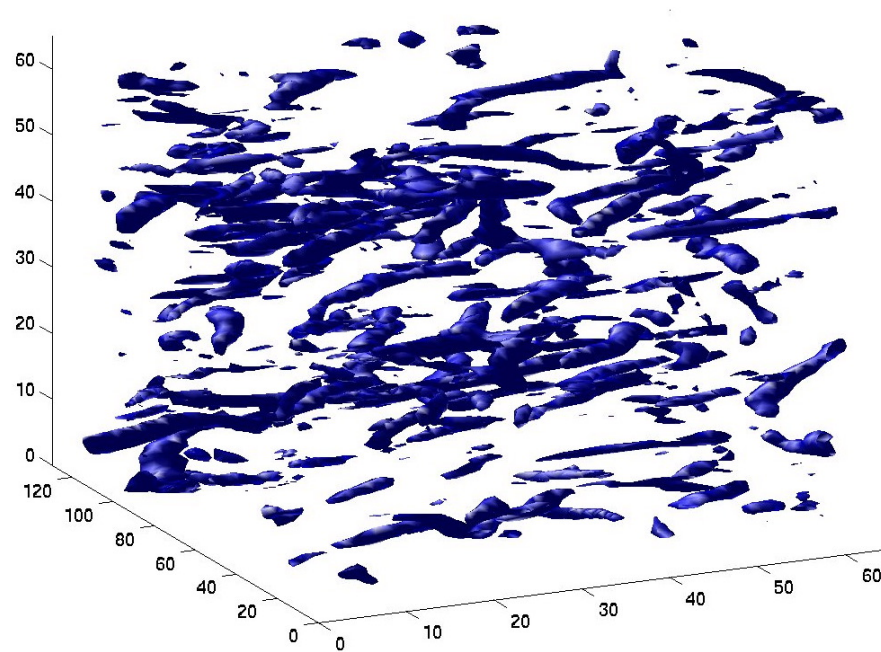
Structures or patterns at multiple scales

- Chaos
- Continuously changing patterns



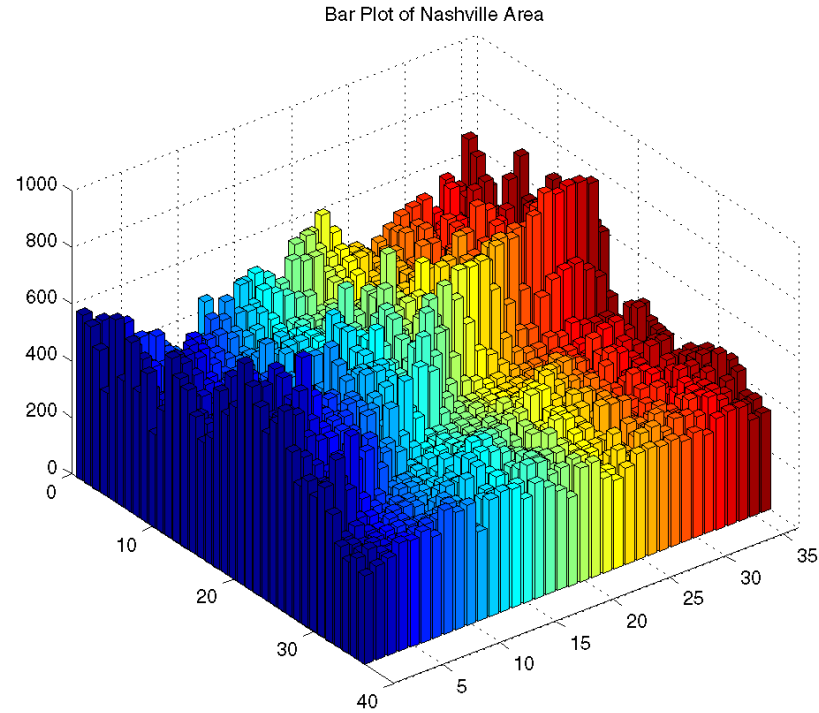
Structures or patterns at multiple scales

- Turbulence - spatial-temporal chaos



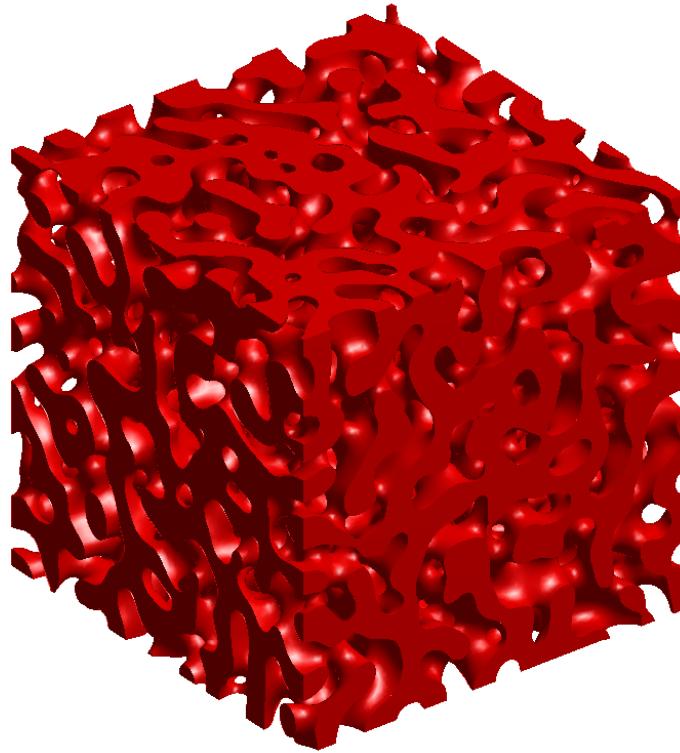
Structures or patterns at multiple scales

- Fractals - topography



Structures or patterns at multiple scales

- Microstructures in materials - transient complexity



We need rigorous mathematical techniques that can do two things:

- Capture those structures that persist under perturbation.
- Identify structures down to a particular scale.

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- Structure of connecting orbits
- Existence of symbolic dynamics
- Existence of homoclinic tangencies
- Singular perturbations
- Time series

2. Bifurcation Theorems

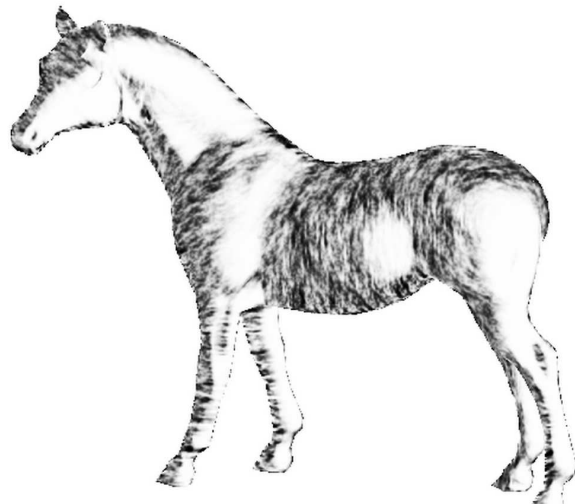
- Homoclinic and heteroclinic orbits

2. Bifurcation Theorems

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- Resolution or Data Compression

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- Homoclinic and heteroclinic orbits
- Resolution or Data Compression
- Computer Graphics



Limiting factors in applying the Conley index

1. Finding index pairs

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1. Finding index pairs
2. Computing the Conley index

Computer Assisted Proof in Dynamics

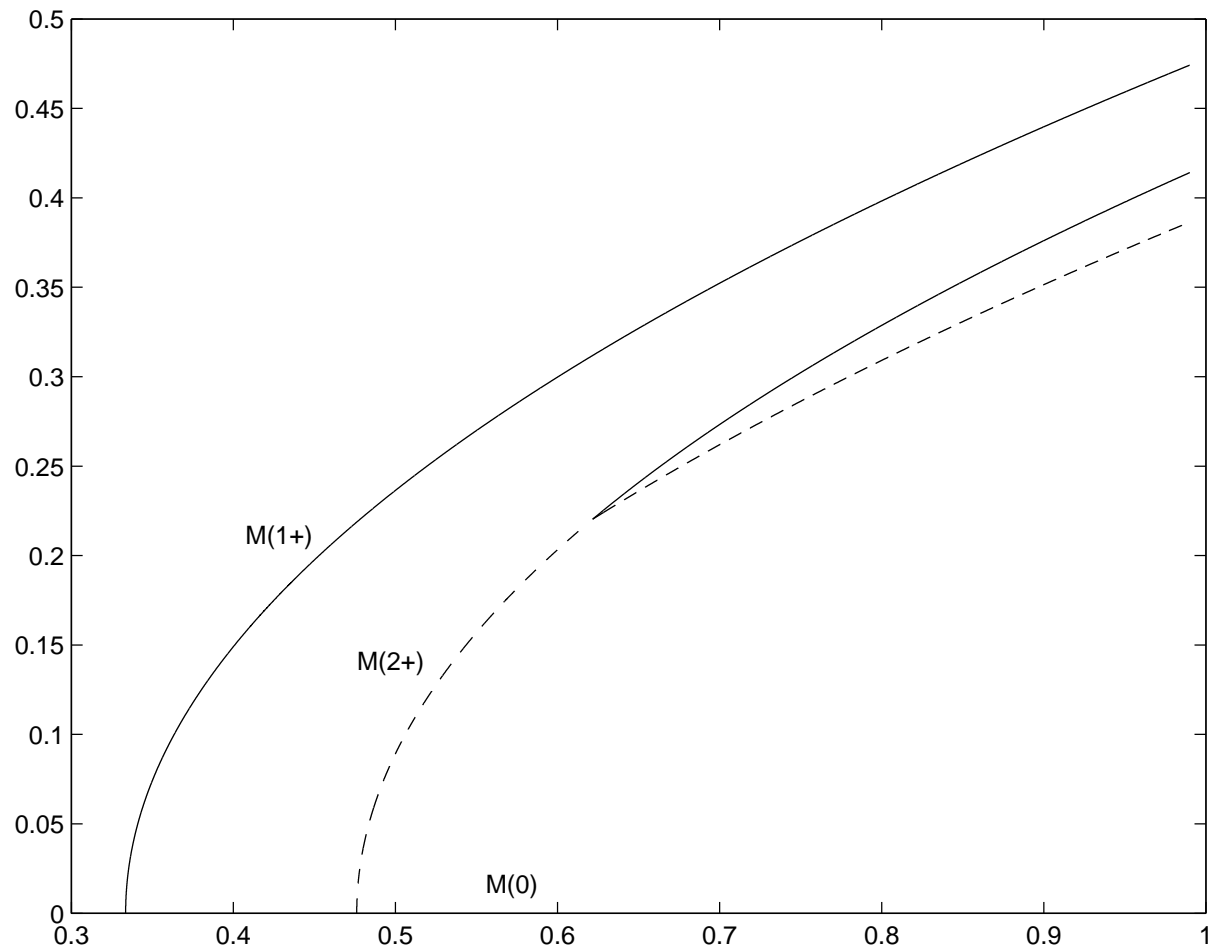
1. Chaotic dynamics in Lorenz equations

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3. Infinite Dimensional Systems
 - **Bifurcation diagrams** (Swift-Hohenberg, Kuramoto-Sivashinsky, FitzHugh-Nagumo)



$$u_t = E(u) = \left\{ \nu - \left(1 + \frac{\partial^2}{\partial x^2} \right)^2 \right\} u - u^3, \quad u(\cdot, t) \in L^2 \left(0, \frac{2\pi}{L} \right),$$

$$u(x, t) = u \left(x + \frac{2\pi}{L}, t \right), \quad u(-x, t) = u(x, t), \quad \nu > 0, \quad (1)$$

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4. Geometric approximations of vector fields.

Conley Index

$f : X \rightarrow X$ a continuous function on a locally compact metric space

$S \subset X$ is *invariant* if for every $x \in S$ there exists a full trajectory $\gamma_x : \mathbf{Z} \rightarrow S$ such that

$$\gamma_x(0) = x, \quad \text{and} \quad \gamma_x(n+1) = f(x).$$

$N \subset X$ is an *isolating neighborhood* if

$$\text{Inv}(\text{cl}(N), f) := \{x \in N \mid \exists \gamma_x : \mathbf{Z} \rightarrow N\} \subset \text{int}(N)$$

Let $P = (P_1, P_0)$ with $P_0 \subset P_1$ be a pair of sets in X . Define

$$f_P : P_1/P_0 \rightarrow P_1/P_0$$

by

$$f_P(x) = \begin{cases} f(x) & \text{if } x, f(x) \in P_1 \setminus P_0 \\ [P_0] & \text{otherwise.} \end{cases}$$

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A pair of compact sets $P = (P_1, P_0)$ is an *index pair* for f if

- $P_1 \setminus P_0$ is an isolating neighborhood
- f_P is continuous.

In order for f_P to be continuous, P_0 must be an *exit set* for P_1 .

Theorem: (Ważewski Principle) If f_P is not homotopically trivial, then

$$\text{Inv}(\text{cl}(P_1 \setminus P_0), f) \neq \emptyset.$$

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Theorem: (Ważewski Principle) If

$$f_{P_*} : H_*(P_1/P_0, [P_0]) \rightarrow H_*(P_1/P_0, [P_0])$$

is not nilpotent, then

$$\text{Inv}(\text{cl}(P_1 \setminus P_0), f) \neq \emptyset.$$

Shift Equivalence

The *homology Conley index* of $\text{Inv}(\text{cl}(P_1 \setminus P_0), f)$ is the shift equivalence class of $f_{P_*} : H_*(P_1/P_0, [P_0]) \rightarrow H_*(P_1/P_0, [P_0])$.

Two group homomorphisms $f : X \rightarrow X$ and $g : Y \rightarrow Y$ are *shift equivalent* if there exist group homomorphisms $r : X \rightarrow Y$ and $s : Y \rightarrow X$ and a natural number m such that

$$r \circ f = g \circ r, \quad s \circ g = f \circ s, \quad r \circ s = g^m, \quad s \circ r = f^m$$

Prop: Let $f : X \rightarrow X$ and $g : Y \rightarrow Y$ be group homomorphisms that are shift equivalent. Then f is nilpotent if and only if g is nilpotent.

Proof: Assume f is not nilpotent. Since $s \circ r = f^m$, neither r nor s are trivial. Assume that $g^k = 0$. Then

$$\begin{aligned} r \circ f &= g \circ r, \\ s \circ r \circ f \circ (s \circ r)^k &= s \circ g \circ r \circ (s \circ r)^k, \\ f^m \circ f \circ (f^m)^k &= s \circ g \circ (r \circ s)^k \circ r, \\ f^{m(k+1)+1} &= s \circ g \circ (g^m)^k \circ r, \\ f^{m(k+1)+1} &= 0. \end{aligned}$$

This contradicts the assumption that f is not nilpotent.

Exercise: $f(x) = 2x$ is not shift equivalent to $g(x) = x$.